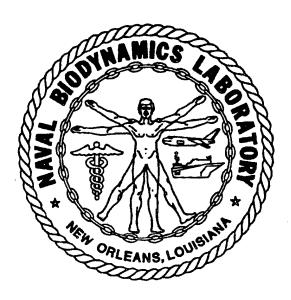
DYNAMIC VARIABLE AND TEMPORARY INJURY CORRELATION FOR HUMAN HEAD AND NECK IMPACT EXPERIMENTS

Brian W. Wamsley, Alvah C. Bittner, Jr., Norman S. Gilbert, Leonard S. Lustick

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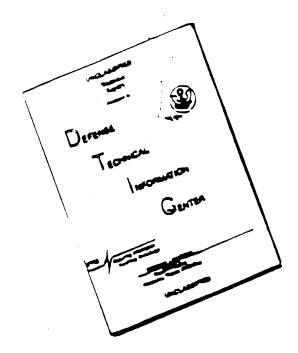
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DYNAMIC VARIABLE AND TEMPORARY INJURY CORRELATION FOR HUMAN HEAD AND NECK IMPACT EXPERIMENTS

BRIAN W. WAMSLEY, ALVAH C. BITTNER, JR., NORMAN S. GILBERT, LEONARD S. LUSTICK

ABSTRACT

The Naval Biodynamics Laboratory (NBDL) has collected a data base describing the head/neck kinematic response of a large number of human subject volunteers to -X, +Y, and -X+Y vector exposures. This paper will present injury-related parameters for the most severe exposures in each vector, together with correlations of these parameters with the medical findings. The parameters presented include axial and shear forces and torques at the occipital condyles, as well as the head injury criterion (HIC number). Moderate (R = .35 and .38) but highly significant (p<.025) correlations were revealed between general (GENFAC) and muscle (MUSFAC) symptom factor variables. These findings encourage continued systematic evaluation of the relationship between the observed injury-related (eg. axial and shear) and medical findings.

INTRODUCTION

The Naval Biodynamics Laboratory (NBDL) has collected a data base describing the head-neck kinematic response of human subject volunteers to -X, +Y, and -X +Y, vector exposures. The goal of this program has been to develop human dynamic and injury response models to impact acceleration as well as to determine the correlation of dynamic responses with physiological effects and injuries. This information is in use for design, construction, and validation of manikins and mathematical models. These products are used to evaluate human protective systems for prevention of casualties from severe impacts (e.g., aircraft crashes and ejections). Thomas, Ewing, Majewski, and Gilbert (1) have previously reported modest correlation between clinical medical effects and sled acceleration and direction. Interestingly, current as well as previous modeling efforts predict that such correlations would be greater, if correlations were made relating "injury-related variables" (eg., maximum shear) with clinical variables (eg., Ewing et al. (2) and Muzzy et al. (3)). This paper will present injury-related parameters for maximum -X,+Y, and -X+Y exposures and their correlations with medical findings.

METHOD

Subjects—The subjects were six Navy enlisted men (ages 19 to 23) who had volunteered for duty as biodynamics research subjects (ie., subjects H131 to H136). They had been selected to be unusually free of skeletal, cardiopulmonary and other medical or psychological conditions which would preclude participation in potentially hazardous environmental research. The subjects were otherwise typical of the general enlisted population. All subjects were recruited, evaluated, and employed in accordance with SECNAV Instruction Series 3900.39 and MANMED Instruction Series 3900.6.



These instructions are based upon informed voluntary consent and meet the provisions of prevailing national and international guidelines regarding proper human experimentation. A more detailed description of the volunteers and their selection is given by Thomas, Majewski, Ewing, and Gilbert (4). Tables 1 and 2 respectively contain selected measured and estimated anthropometric parameters for the volunteer subjects.

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Experimental Design -- Subjects were exposed sequentially to blocks of G(-x), G(+y) and G(-x+y) sled profiles with respective maximums of 15, 7 and 9Gs. To minimize the effects of initial conditions each subject was always run in the neck-up, chin-up condition which is standard at NBDL (Ewing et al. (5)). Subjects were medically rexamined by a physician immediately prior to, shortly after, and 24 hours postrun (or until the abatement of any significant medical findings). This information was recorded for later computer analysis. Retrospective review of the post run medical log yielded five categories of symptoms and physical findings in keeping with that reported by Ewing et al (2). These were (1) hours of muscle soreness; (2) hours of muscle stiffness; (3) hours of headache; (4) hours of backache, and (5) other.

Apparatus — An Bendix Hyge(R) pneumatically driven .3048m diameter accelerator a was used to accelerate an approximately 1.2m by 3.7m multivectorial reledit which was a rail mounted non-Delrin AF(R) pucks. The acceleration stroke rish limited to 1.52m and sled mounted brakes were not used. Thereffective drag is about .2G and the sled was allowed to coast to a stop. Total rail length available is 213m. The impact direction (-X,+Y or -X+Y) was determined by rotation of the multivectorial sled.

The subjects were restrained in a nominally upright position by shoulder straps, a lap belt and an inverted "V" pelvic strap tied to the lap belt. Upper arm and wrist restraints were used to prevent flailing. Figure 1 illustrates the basic restraint system which was used for the three vector directions.

Figure 1 about here a line

Experimental Measurements -- The dynamic variables presented in this paper were derived by integrated accelerometer and cinephotographic measurement systems (Seemann and Lustick, (6). The accelerometer system yielded measurements using nine piezoresistive accelerometers mounted on a "T" shaped plate at the mouth and six accelerometers mounted on a T-plate at the spinous process of the first thoracic vertebral body (T(1)). The configuration of the accelerometers on the T-plate and the error propogations associated with this method for determining linear displacement, velocity, acceleration and angular orientation, angular velocity and angular acceleration components of a rigid body have been described (Becker and Willems, (7)). The cinephotographic system with the accelerometer system has been previously described (Becker, (8)).



In order to compare subjects at similar points in the anatomy, it is required to define a head anatomical coordinate system and a T(1) anatomical coordinate system (Thomas, (9)). These anthropometric coordinate systems are related to the instrumentation coordinate systems by three dimensional x-ray anthropometry on each subject (Ewing et al. (5)).

One reference frame for the entire series of experiments is fixed to the laboratory. This is established by first defining a sled coordinate system in which the origin is a benchmark permanently machined into the sled structure. The +X axis is parallel but in the opposite direction to the thrust vector of the accelerator. The +Z axis is parallel to gravity and positive upward and the +Y axis is established so that the axes form an othogonal right hand system. A second frame of reference is fixed to the anatomical axes of the head as illustrated in figure 2. (cf. Thomas, (9) for more detail). Both coordinate systems used in this study are right handed where X, Y, and Z axes are taken in that order.

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Injury-related variables which will be tabularly reported for all runs include maximum and minimum:

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And Linear force components (relative to head X, Y, and Z) over a sled run acceptation head-neck junction (condyles) and approximation of the head-neck junction o

west-irranes and a smith was rall mounted on Lie ria AVII and west-irranes and resultant forces at the head-neck junction.

Tr>HIC. component and resultant value for window widths of less than 200 straims. a law fill and the formula of the formula of the fill that the fill the fill that the fill that the fill that the fill that the fill the fill that the fill that the fill that the fill the fill the fill that the fill that the fill the fill the fill the fill

In addition, plots comparing the time course for these variables for the subjects with the greatest and smallest head mass parameter (H132 and H135) will be provided for illustration of the range of responses. Time courses for these and other selected variables will be graphically provided for a typical subject (H134). Only linear and torque force components will be related to the medical log symptoms by correlational analysis

int designate RESULTS

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Evaluation of the data was conducted in three phases. During the first phase, dynamic variables believed to be injury-related were examined. Medical variables were analyzed during the second phase. The third phase was concerned with correlation of the injury-related variables and medical variables.



Injury-Related Variables.

Injury-related dynamic variables were tabulated and graphically analyzed during this phase of evaluation. Graphical analysis revealed, as might be expected that the injury-related variables tended to increase in magnitude, with increasing exposure (G) levels for the three vector directions. Figures 3, 4, and 5 illustrate time courses for respective changes in the resultant force, resultant torque and HIC variables for a ranger of red 2 to a 15.6 G(-X), 5.3 to 7.0(+Y), and 9.3 to 11.4(-X+Y). It should be pointed out that, occasionally, experienced forces may be substantially greater for a relatively lower sled G level than at higher levels for the same subject ... (e.g., H132 at 13 vs. 15 G(-x) in Appendix A). The trend toward increasing injury-related magnitudes with increased exposure limits focused our attention toward the higher levels in later analyses. Tiva. hanc tistor. A second trame of to elebor

among bload axes of the head as impartance in tights 2. of Thomas. more _oetail. Lysic collegiants of extens used to this emon ore there is Figures 3, 4, and 5 about here

Graphical analyses also indicated that individual differences play a role in experienced forces under nominally the same sled force conditions. Figures 6, 7, and 8 show shear and axial forces as well as resultant torque time-courses for subjects with greatest (H135) and least (H132) head mass parameters. Over nominal 15G(-x), 7G(+y) and 10G(-x+y) conditions, the largest headed subject (H132) tended to experience greater stresses than the smallest subject. The larger subject, as will be seen later, also reported greater medical problems post-run. The apparent role of individual differences focused our attention on their importance in later analyses.

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Figures 6, 7, and 8 about here

rica manaca (I^Me The results of graphical analysis suggested tabulating experienced injury-related variables for the greatest experienced level for each vector and each subject. The appendix contains a portion of this tabulation.

Medical Variables

The medical variables were tabulated and analyzed during the second phase of evaluation. Table 3 provides the basic data by subject and run. Examining this table, it may be noted that some runs were uneventful while other runs resulted in clusters of symptoms (muscle soreness and muscle stiffness tend to go together). It may also be seen that about 30 percent of the impact runs resulted in some significant symptom. The nature and frequency of such findings were similar to that reported by Thomas et al. (1) where significant symptoms were reported for about 40 percent of the runs. This clustering of symptoms suggested condensing the symptoms into "factors" which are more syndrome in character.

Table 3 about here.



A principal factor analysis was conducted on transformations of the variables shown in Table 3. The first four variables (hours of muscle soreness, through hours of backache) were transformed (log(x)+1) to reduce skewness and theoretically enhance linearity. The last variable was coded as "0" tor "1" to respectively denote the absence or presence of other symptoms. The transformed variables are subsequently labeled MUSOR, MUSIF, HEAD, BACK, and OTHER for purposes of identification. The analysis resulted in evidence of a strong first factor (syndrome) which accounted for 50.8% of the variance across the symptoms (eigen-value of 2.53). A second factor (syndrome) was also suggested which added an additional 25.4% of the variance (eigen-value of 1.27). For purposes of this investigation, it was decided to consider results for both the one and two factor solutions with the injury-related variables. Table 4 provides the intercorrelation of the medical variables as well as their loadings (correlations) on the derived factors.

TABLE 4 about here. It where here

The factor from the first solution we termed GENALFAC. Those from the second were respectively termed MUSFAC and OTHRFACT. These terms were selected to reflect the relative prominence of general, muscular, and other symptom loadings on the respective factors (cf, Table 4).

Correlation of Medical and Injury-Related Variables reported steems medical problems peachts.

stepwise regression analysis was applied to each of the three medical factor variables (i.e., GENFAC, MUSFAC and OTHRFAC). Interestingly, prior to the analyses, it had been planned to force specific variables (Maximum Shear, and absolute Axial Forces); however, these were selected from GENFAC and MUSFAC by the stepwise procedure. We also correlated G-level with these factor variables, but maximum shear or axial force showed a higher correlation. For OTHRFAC, the Shear and Axial Variables were unpredictive and a broad range of other variables were condidered (e.g. Torques at the condyles, etc.). Analyses for GENFAC and MUSFAC represent planned analyses while that for OTHRF was exploratory.

GENFAC.

Regression analysis with the shear and axial variables yielded a significant multiple $\underline{R} = 0.354$ (F(2,57) = 4.07, p<.025). The prediction equation is:

$$GENFAC = -.7194 + .0027Z + .0028S$$
 (1)

where Z is the greatest negative axial force (Newtons) and S is the maximum shear (Newtons). The coefficient for Z and S significantly exceeded their respective standard errors (F(1,57) = 5.20, p<.05) and F(1,57) = 7.83, p<.01). Equation (1) predicts an increasing GENFAC with increasing sheer force and lessening of the axial force which tends to hold the head on the neck.



MUSFAC. Regression analysis with the axial and sheer variables yielded a significant multiple R = 0.378 (F(2,57) = 4.75, p<.012). The prediction equation is proude notes of prediction the prediction is proude notes of prediction in the prediction of the prediction

at M**MUSFAC = 4.8435 4.0025Z +:0029S** are ab**(2)** to or become the lab. Symmtomic The transformed variation are subscibled to labeled Million.

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where Z and S are as defined for equation (1). Again the coefficient for Z and S-significantly exceed their respective standard errors (F(1,57) = 4.44, p<05 and F(1,57) = 8.26; p<01). Equation (2) predicts increases in MUSFAG under conditions similar to that of (1).

OTHRFAC

Initial regression analysis with axial and shear forces yielded no results of consequence. Subsequent stepwise analysis was only relatively more productive; the best single predictor was the maximum torque about the X-axis (R =.18, p>.16) which even in conjuction with a second predictor (greatest negative torque about the S-axis) yielded no improvement (R = 0.236, p>.19). The resulting OTHRFAC prediction equation weight for the torque variables were in the direction of increasing with increasing torque magnitude.

DISCUSSION

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This report considered the relationship between variables believed to be injury-related and their correlation with medical findings over (-X), (+Y) and (-X+Y) impacts. Initial analyses focused upon relationships within the medical variables. These focused our attention on the relationship between the injury-related and medical factor variables. Our discussion of these results will follow this pattern of analysis and will preceder conclusions.

Injury-Related Variables.

The graphical analyses of these variables revealed two relationships. First and not unexpectedly, the injury-related variables tended to increase with the nominal magnitudes for each vector direction exposure (cf, Figure 3, 4 and 5). This focused attention on the nominally most severe runs for each vector direction in the NBDL database.

The second finding of the graphical analyses was the apparent relationship between the injury-related criteria and anthropometery (i.e., head mass) seen in Figures 6, 7 and 8. Subject H132 with the largest head mass experienced larger forces and torques than the smallest (H135). These subjects also differed on other variables in a similar pattern (e.g. neck length) and consequently the observed systemic differences can not be uniquely ascribed to head mass. (However, the report by Muzzy et al. (3) certainly indicates a strong relationship between head mass and resultant forces and torques.) Interestingly subject H134, with an intermediate head mass reported no adverse effects and had a particuarly short neck.



Currently, we are initiating correleration of variables across subjects in an effort to be more definitive. Certainly, these results point to consistent individual differences which are embedded in our later analyses.

Medical Findings 3435 4.00352 4.007

and Summary coffether medical findings revealed apparent clusters of reported symptoms (cf. "Table 3). These clusters could reflect subject tendencies at complain; subject differences in "injury"; or a combination of both. The tendency for subject H132 (largest head mass) to report more often than H135 (smallest) did give some initial support for the view that actual injury differences are involved. Factor analysis was performed to identify and condense the symptoms prior to correlation analyses with the injury-related variables. Table 4 standarized the correlation between the transformed amedical variables and factors which resulted from this analysis.

Regression Analyses

The correlational analyses relating the medical factors and injury-related variables provided strong evidence of their relationship. Both the GENFAC (general) and the MUSFAC (muscle) factor variables exhibited moderate but highly significant (p<.025 and .012 respectively) correlation with the same sheer and axial forces experienced by the subject (r = .35 and .38). The prediction equations for these two variables were also similar equation (cf, equations (1) and (2)). These similarities, were in part not unexpected as GENFAC may theoretically be viewed as a comparison between MUSFAC and OTHRFAC. However, the correlation bewteen MUSFAC and GENFAC was relatively higher than expected (r = .86). In any case, the relationship between the injury-related dynamic variables and the medical reports is supported by the results in the paper. The choice of symptom cluster does remain open for future work.

CONCLUSION

part properties appeared a property of the contraction of the

The findings of this report encourage continued systematic evaluation of the relationship between observed injury-related variables and medical findings. Certainly, the results of this report indicate a moderate but highly significant correlation between reported symptoms and the maximum shear and greatest negative axial forces. Based on this report, additional correlation analyses relating individual differences in anthropometeric variables (head and neck size) with the injury-related and medical variables appears a fruitful direction for future work. Perhaps equally productive might be correlation of such variables and injuries experienced by civilian and military personnel in impact environments. We encourage other researchers to focus on non-permanent symptoms following impacts and their relationship with subject variables.



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Table 1. Subject Anthropmetric Variables

Subject	Age (Yrs)	Height (cm)	Weight (kg)	Head Circumference (cm)	Head Length (cm)
H131 H132 H133 H134 H135 H136	20 21 20 20 23 19	167.0 172.9 161.7 178.3 171.6	67.7 80.0 61.4 75.5 69.1 89.1	57.5 57.9 56.1 56.6 53.5 56.4	19.6 19.7 19.4 19.4 17.9

Table 2. HEAD MASS PARAMETERS

SUBJECT	MASS*	CENTER OF MASS** (cm)			OF INERT	PRINCIPAL MOMENTS** OF INERTIAL (Kg-cm(2))				
•		x	Y	Z	. X'	Υı	Z '			
H131	4449	0.84	- .06	3.17	219.8	235.0	152.9			
H132	4523	0.84	06	3.18	225.9	241.5	157.2			
H133	4170	0.82	05	3.10	197.3	211.0	137.3			
H134	4278	0.83	05	3.13	205.9	220.1	143.3			
H135	3791	0.80	05	3.00	168.3	180.0	117.1			
H136	4235	0.83	05	3.12	202.4	216.4	140.9			

*Mass estimated from head circumference and length (Kaleps et et al., 1984)

**Center of mass and principal moments estimated via isometric analysis (Bittner, 1986)



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3948	A	H131	. 1	0.2G(-	۲) ₍ ا				e in the con-	. 54	•					
3987	• •	H131	1	3.7G(-	ረ)	•	****	·		en en e		7.7				
3990		H131	*** 1	4.5G(-)	۲)				, 					را بد		
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4089		H131		5.1G(+)	7)				•				Ĭ.			•
4109		H131	t	6.2G(+)	7)·				i k				,			
4124		H131	4 5	7.2G(+)	7)	•		• •								٠ ـ ـ
4242		H131	•	7.3G(-2	: / :+v1		•				* *		•			YES*
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4251	•	H131	_: 1	0.2G(-	2477						* 4		• .			•
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3950		H132	7	3 . 6G (-x	•) .:			59								
3957		H132	•	4 • 7G (−x	()	8	•	68			7	*5		. •		
3982		H132		4 · /G(-x	()	33		33 =		*.	4					
4090	·	H132	-	5.6G ₁ (-x	() 4	19	,	- 49	***		' - T.					
4110		H132		5.1G(+y	()	57		67 s					67			
4128		H132		6.1G(+y	") /	70	~	70			. **	•	0,		. ,	Carried In
4261		H132		7.1G(+y	") - 4	17										1
4297			parameter series	9.0G(-x	+y)	- ei-Peren a							T			
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. 4500		H132	1,	1.1G(-x	(+y)	.48		200			33		" An			*
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3963		H133	1:	3.4G(-x)							•				
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4093		H133		5.1G(+y)						٠.					-
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4236		H133	7	7.3G(-x	, +v)	44	•	A A	,		6					
4240		H133	9).lG(-x	+v)	95	•	44	\	`	2					
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3993		H134	10	2G(-x) .	1						٠.				
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3968	·	H134	14	3G(-x	'											
3983		H134	. 15	6G(-x	'		٠.									•
4097		H134	5	0G(+y	΄ ΄	•			:	•						•
4112		H134	. 6	lG(+y	(, 			•						
4126		H134	. 7	·1G(+y										•		· .
4264		H134	a	3G(-x-	/ Lv+\	•			•	:						
4298		H134	10	• 1G(-x-	ry)		_	-	-							
4307		H134	. ±0	• 4G(-x-	LA)							•				75 846
			. 4.4.	• 4G (-X-	ry)		•									
		•	•													

^{*} two premature ventricular contractions after impact
** right bundle branch block for three complexes impact
*** felt "stunned" after impact, complained of dizziness for 2 days



RUN NUMBER	SUBJE NUMBER		MUSCULE SORENESS (HOURS)	MUSCLE STIFFNESS (HOURS)	HEADACHE (HOURS)	BACKACHE (HOURS)	OTHE (YES/N
	. · · · · · · · · · · · · · · · · · · ·	,			"		
3916 3955 3965 3970 4095 4114 4131 4314 4316	H135 H135 H135 H135 H135 H135 H135	10.3G(-x 13.6G(-x 14.6G(-x 15.6G(-x 5.2G(+y 6.1G(+y 7.3G(+y 9.1G(-x	c) c) c) 7) 7) 44 c+y)	18	الجو فاتعد		
4918 3953 3962 4098 4142 4153 4247 4263	H136 H136 H136 H136 H136 H136	10.2G(-x 13.3G(-x 14.1G(-x 5.1G(+) 6.0G(+y 7.1G(-x 9.2G(-x	33 37 47 2) 31 31 31 31 31 31 31 31 31 31 31 31 31	20 33 47	47	47	YEŞ

**** one premature venticular contraction 22 seconds after impact





TABLE 4. MEDICAL VARIABLE INTERCORRELATIONS AND FACTOR LOADINGS

		er er er er er Er er er er er er er er er er er Er er er er er er er	TOTAL MARKET CONTROL MARKET MA					
-	MEDICAL VARIABLES	3	ONE FACTOR SOLUTION FACTOR	TWO SOI FACTOR 1	FACTOR UTION FACTOR 2			
MUSOR	MUSOR MUSIF HEAD F	BACK OTHER	(GENFAC)	(MUSFAC)	(OTHRFAC)			
MUSIF HEAD BACK OTHER	.800 1.000 .498 .412 1.000 .402 .286 .588 1	.000 .289 1.000	.856 .775 .797 .717 .232	.901 .929 .549 .403	.169 032 .629 .715 .823			





Figure 1, Illustration of the Restraint System as implemented on Subject H134.



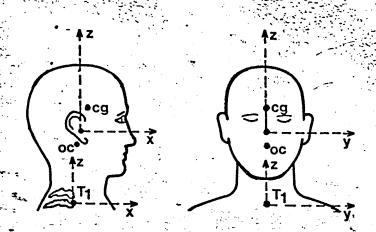


FIGURE 2. HEAD AND T1 ANATOMICAL
COORDINATE SYSTEMS

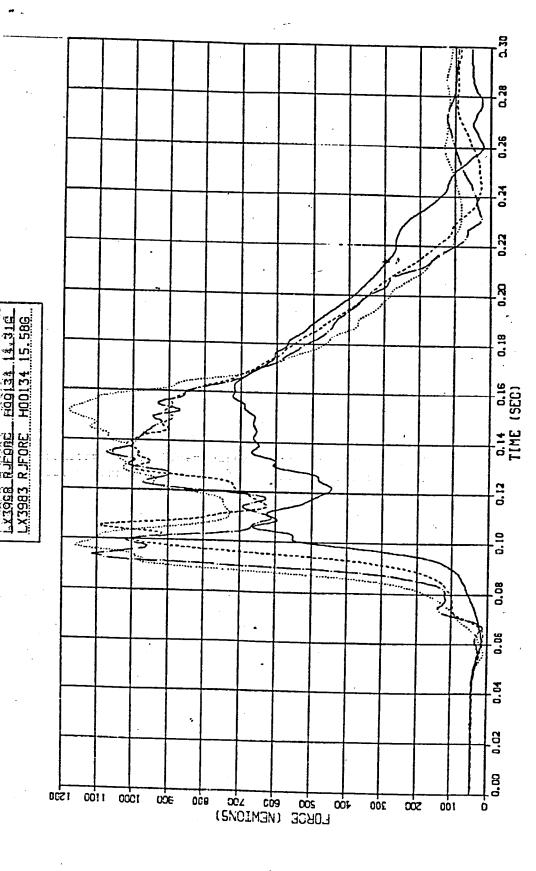


Figure 3. Resultant Force Time-Courses Across -X, +Y, And -X+Y Yector Directions And Selected Accelerations For H134

COORDINATE



resultant force for minus X sled runs





RESULTANT FORCE FOR PLUS Y SLED RUNS

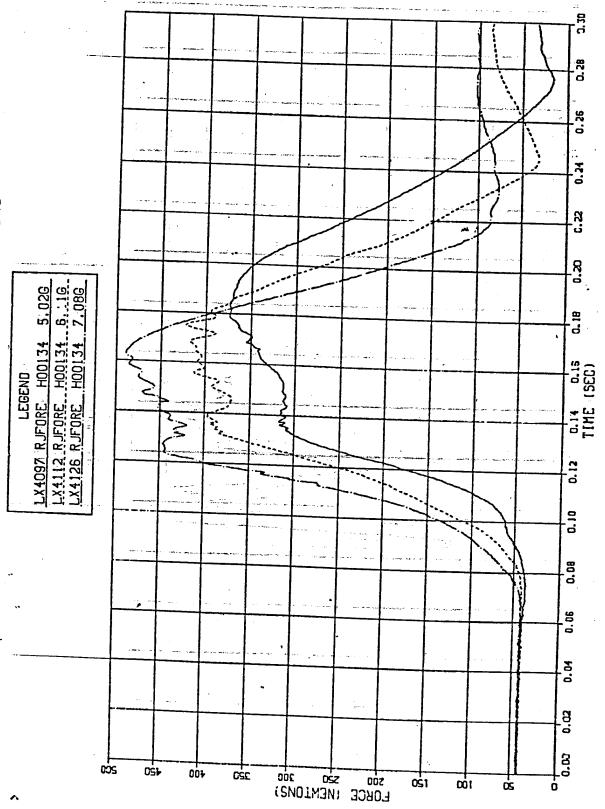




Fig 36



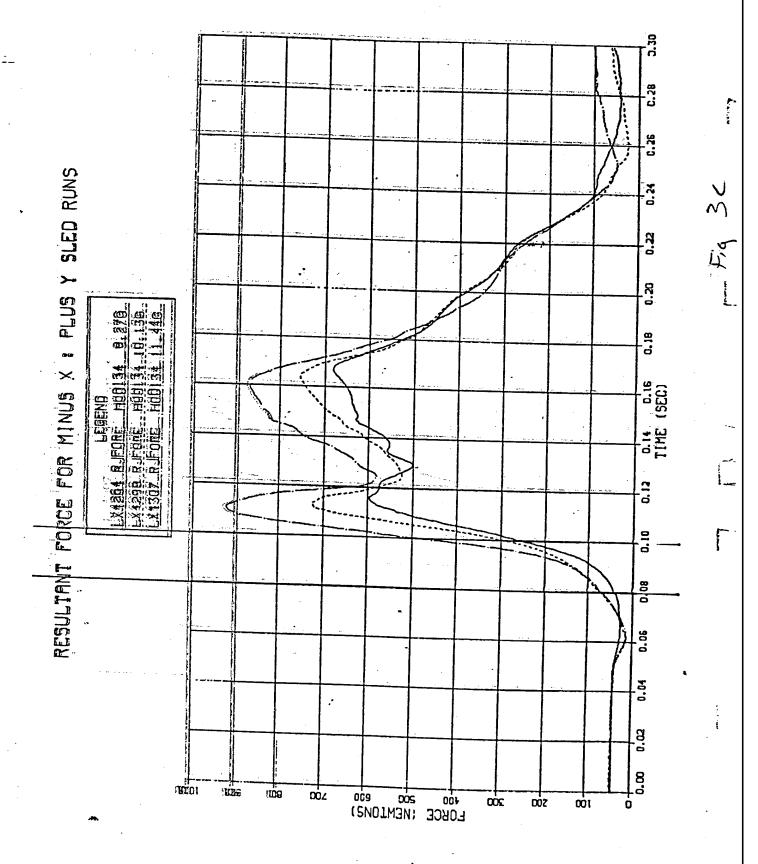


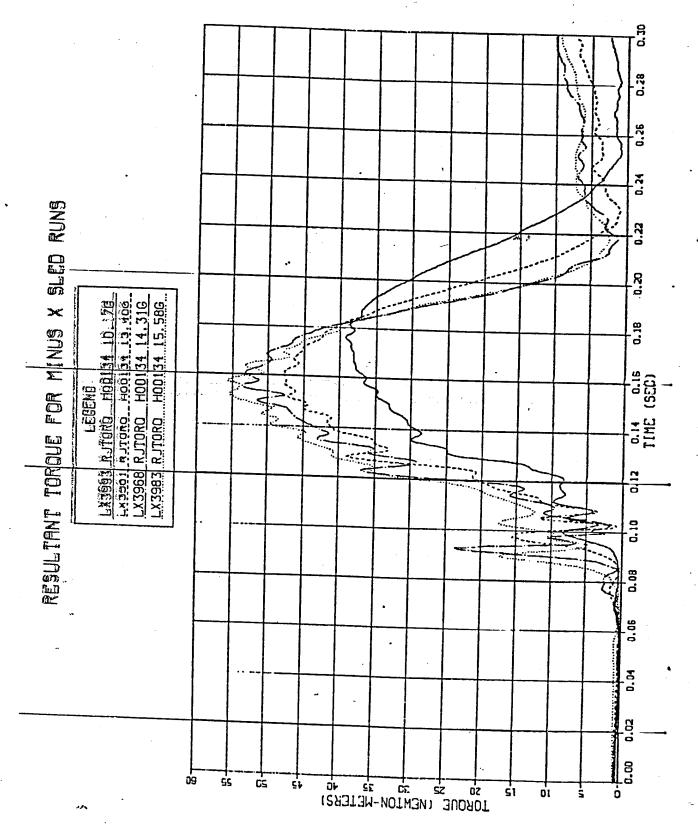


Figure 4. Resultant Torque Time-Courses Across -X, +Y and -X+Y

Vector Directions and Selected Accelerations For H134



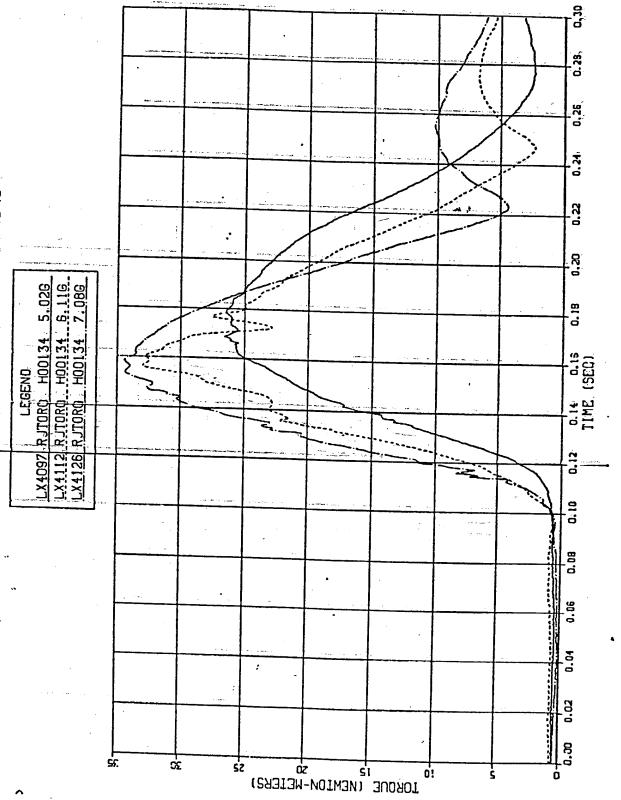








RESULTANT TOROUE FOR FLUS Y SLED RUNS







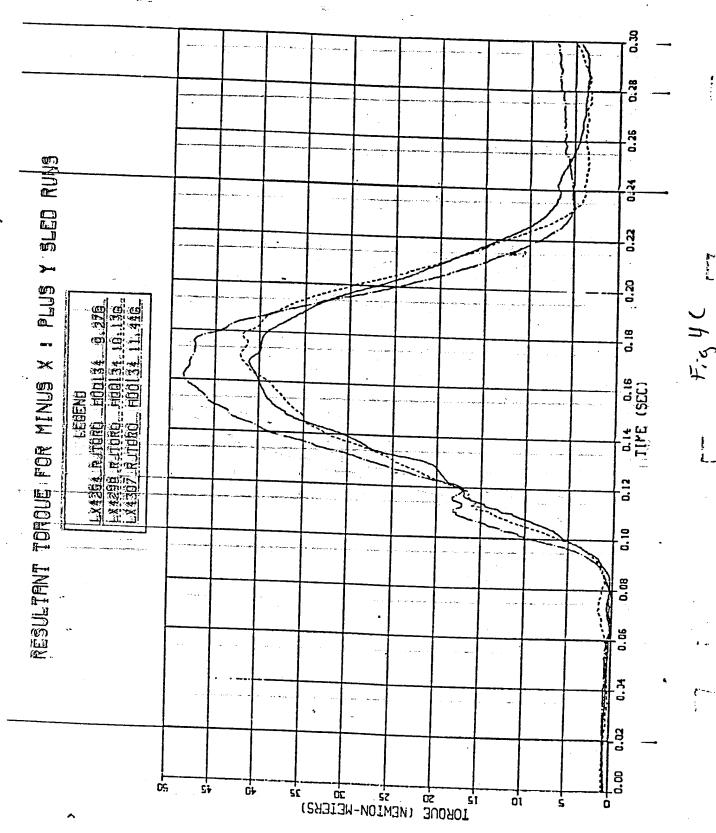


Figure 5. Head Injury Criteria (HIC) Time-Courses Across -X, +Y and -X+Y

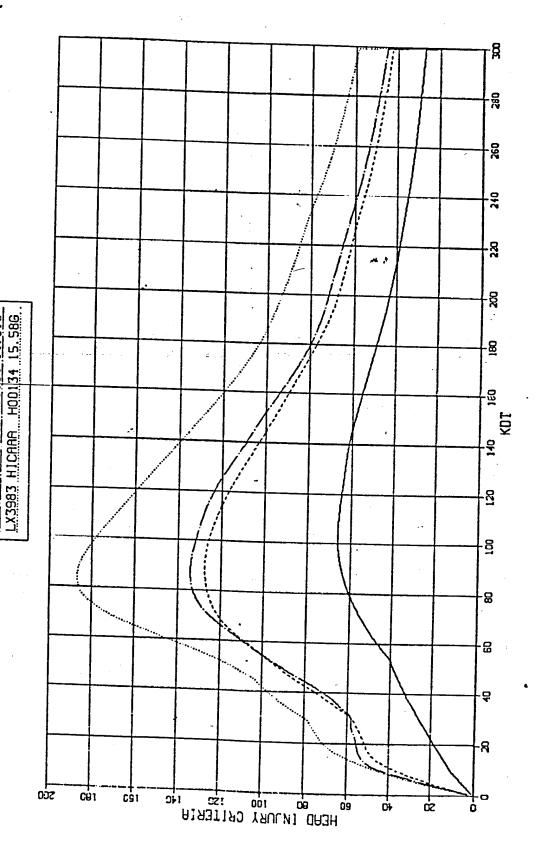
Vector Directions and Selected Accelerations For H134.





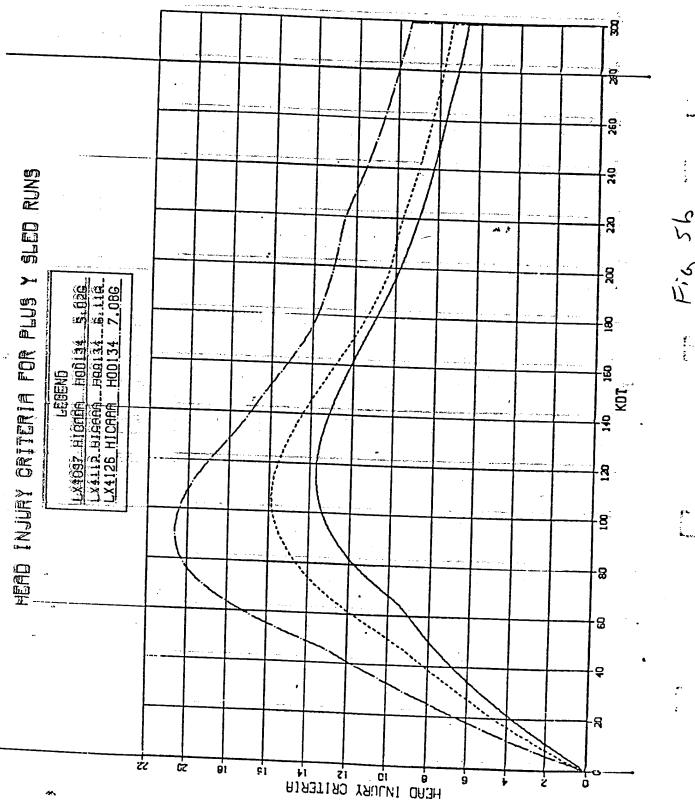
HEAD INJURY CRITERIA FOR MINUS X SLED RUNS

LEGEND LX3993 HICARA HOD134 10,176











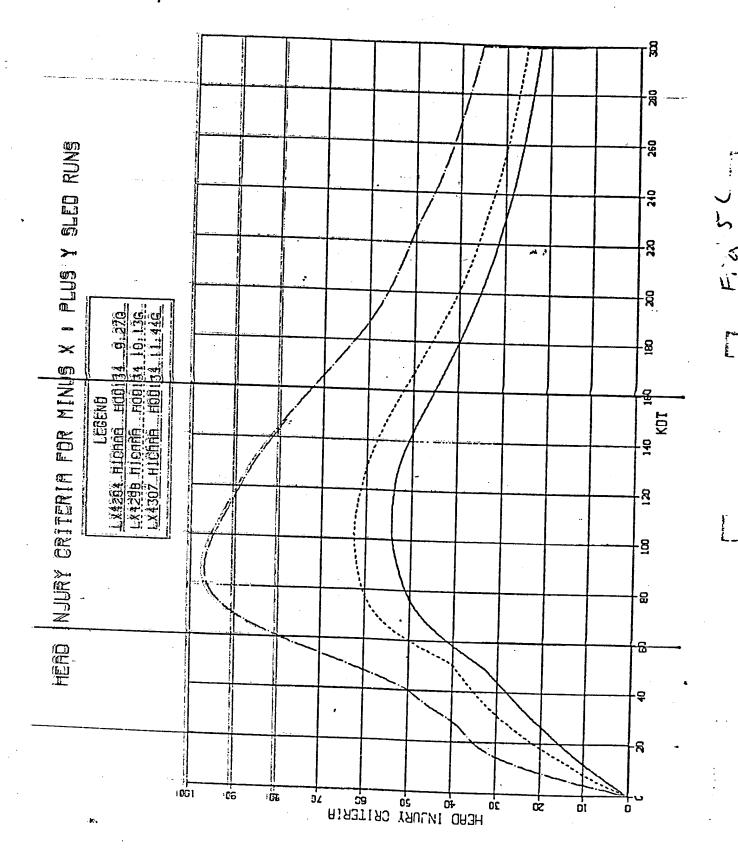


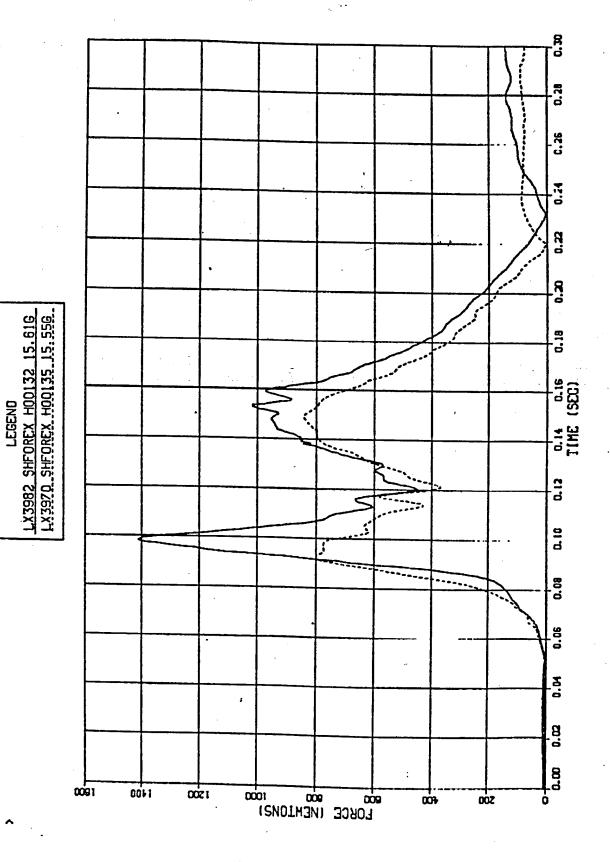


Figure 6. Shear Force Time-Course Comparisons for Subjects with Large (H132) and Small (H135) Heads Across Selected -X, +Y, and -X+Y Impacts





SHEAR FORCE FOR MINUS X SLED DIRECTION







SHEBR FORCE FOR MINUS X : PLUS Y SLED RUNS

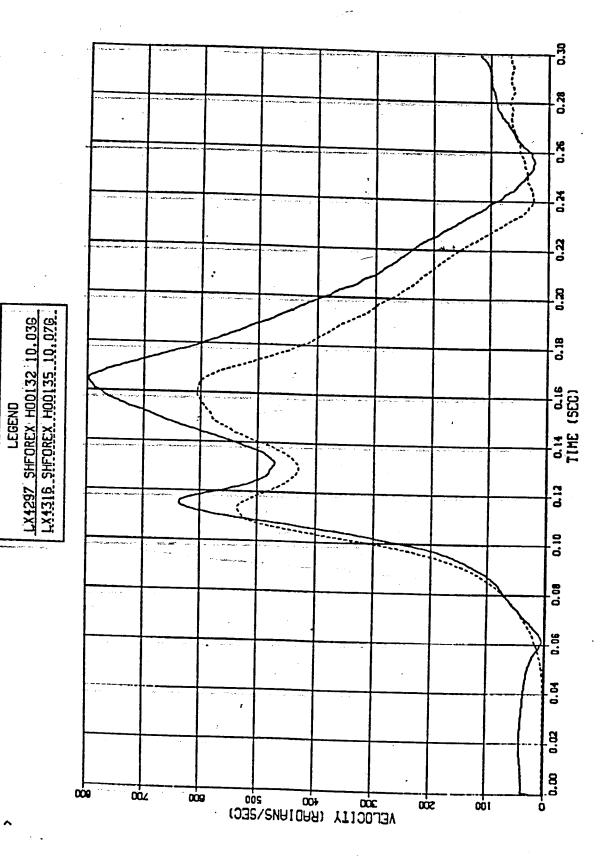




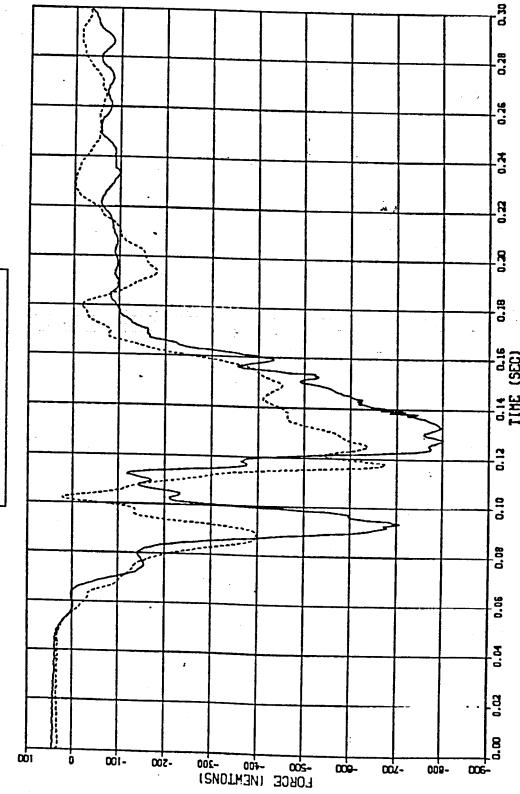
Figure 7. Axial Force Time-Course Comparisons for Subjects with Large (H132) and Small (H135) Heads Across Selected -X, +Y and -X+Y Impacts





AXIAL FORCE FOR MINUS X SLED DIRECTION

LX3982 FJCOXS HO0132 15,616 LX3970 FJCOXS HO0135 15,556





Fin J



FORCE FOR PLUS Y SLED DIRECTION

LX4128 FJC0XS H00132 7,146 LX4131 FJC0XS H00135 7,256

051

001

R c.14 c.16 TIME (SEC) 0.12 , 0. 0.0 2 8.8 8.6

FORCE INEMTONS!

00Z-

052-

-200

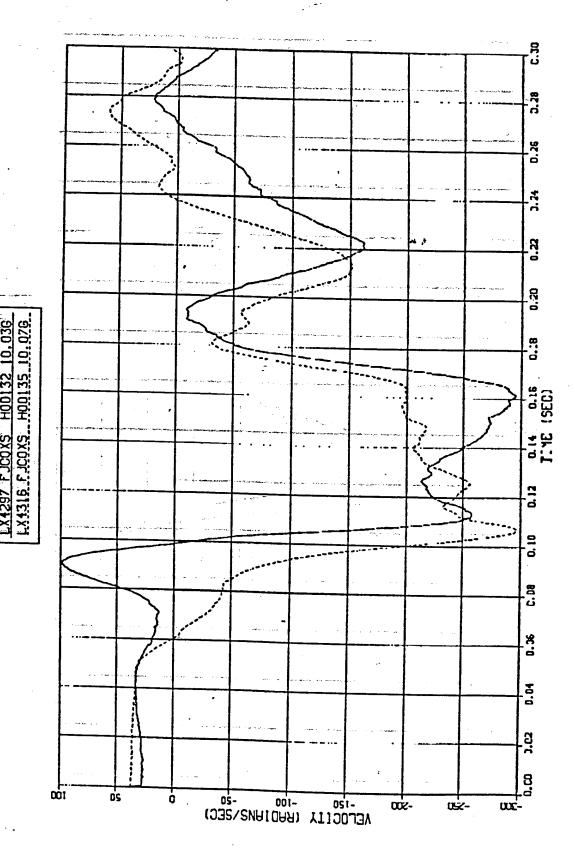
O2C-



Fig 76



AXIAL FORCE FOR MINUS X : PLUS Y SLED RUNS







AXIAL, FORCE FOR MINUS X : PLUS Y SLED RUNS

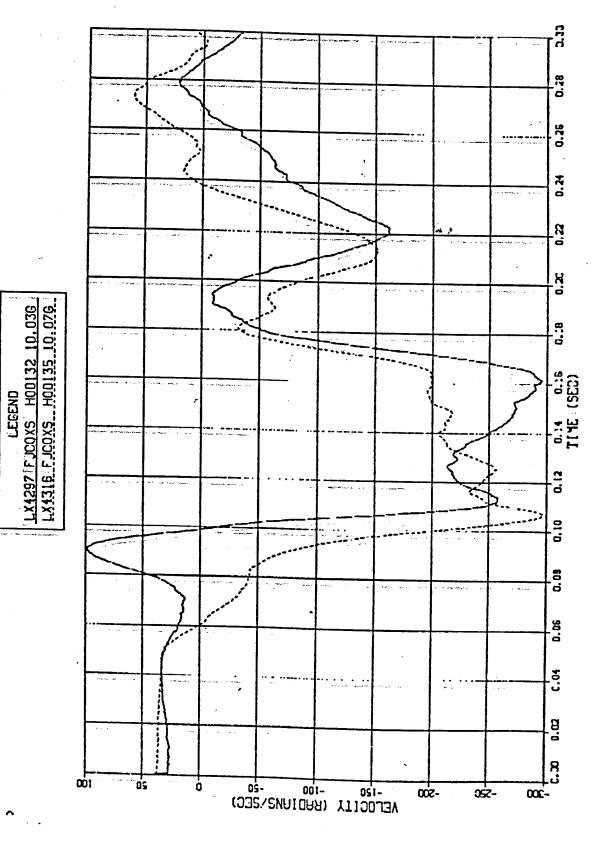
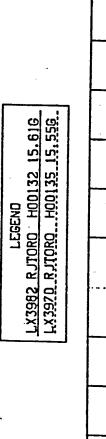


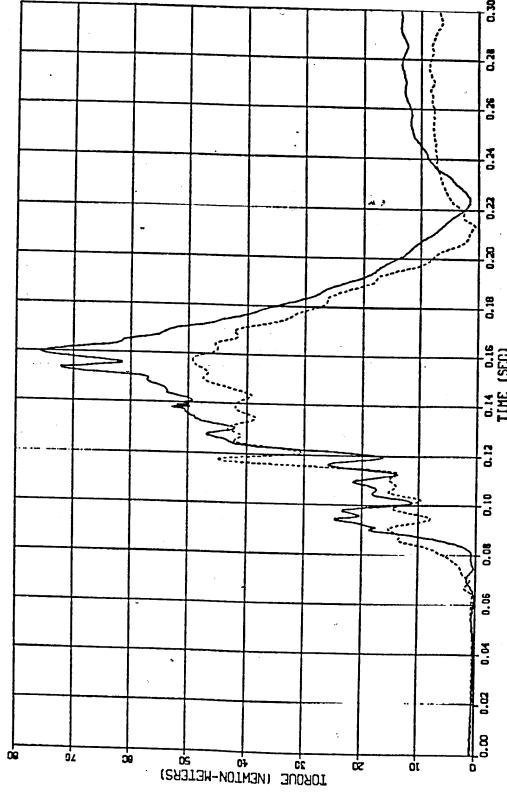


Figure 8. Resultant Torque Time-Course Comparisons for Subjects with Large (H132) and Small (H135) Heads Across -X, +Y and -X+Y Impacts



RESULTANT TORQUE FOR MINUS X SLED RUNS

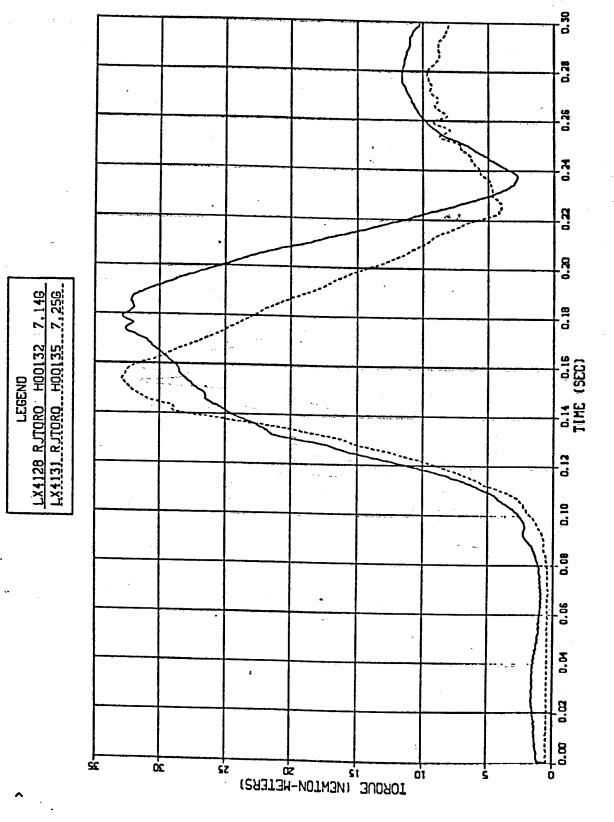








RESULTANT TOROUE FOR PLUS Y SLED RUNS

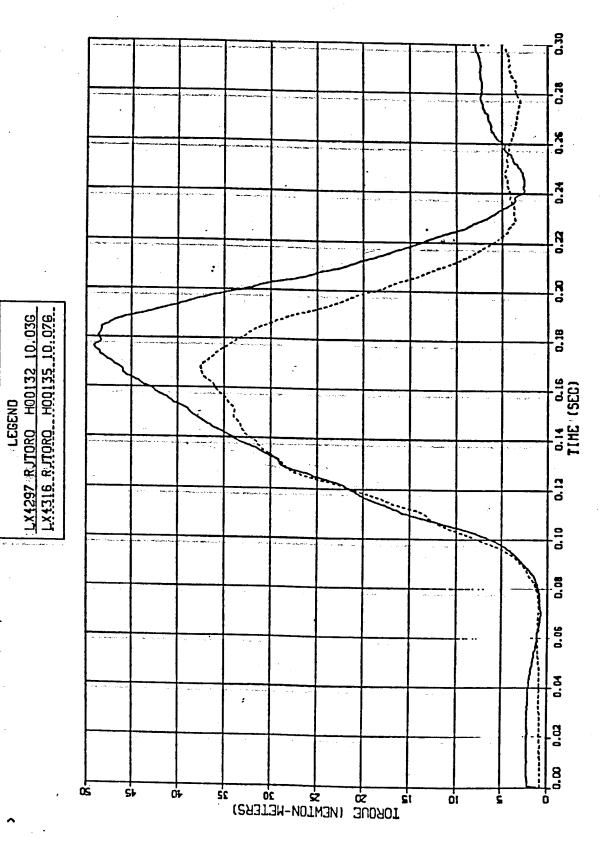




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RESULTANT TORQUE FOR MINUS X : PLUS Y SLED RUNS





APPENDIX

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SUBJECT (H131-H136) INJURY-RELATED VARIABLE SUMMARY TABLES FOR SELECTED -X, +Y, AND -X+Y IMPACT ACCELERATIONS AT NBDL



SUBJECT HOO131

*** Head Anatomical Configuration ***

Head Mass: 4.449 Kg.

Head Center of Gravity: X = +0.0084 Y = -0.0006 Z = +0.0317 Meters Head / Neck Center of Gravity: X = +0.0190 Y = +0.0000 Z = +0.5800 Meters

Eignvalues: 1 = +0.02198 2 = +0.02350 3 = +0.01529

Principal Axis Matrix +0.82900 +0.00000 +0.55920 +0.00000 +1.00000 +0.00000 -0.55920 +0.00000 +0.82900 Moment of inertia matrix in A.C.S. +0.019887 +0.000000 +0.003101 +0.000000 +0.023510 +0.000000 +0.003101 +0.0000000 +0.017381

		Run LX	evel 3908	Run LX	evel 3948		eve1 3987	15 G-L Run LX	
5	V 4		Min				Min		
						139.87-			
Force			-76.47					38.80	
Force			-404.53					45.03	
Force	Kesuit	/88.51	4.63	980.34	15.66	1225.57	11.25	1180.26	14.98
		10.01	evel	12 ()	ouo I	14 0 1	1	15 C Lov	<u> </u>
							evel	15 G-Lev	
			3993				396887		
		Max		Max	Min	Max	Min	Max	Min
Torque	X-Axis	8.66	-6.95	6.70	-2.49	7.56	-4.3 8	10.90	-3.77
Torque	Y-Axis	27.48	-45.81	11.48	-51.92	13.69	-58.89	13.10	-55.22
Torque	Z-Axis	1.44	-2.96	0.89	-1.58			2.56	
Torque	Result	45.81	0.41		0.09		0.10		
					-				
		10 G-L	.evel	13 G-L	evel 💮	14 G-L	evel	15 G-Lev	el
			3993		3961	Run LX	evel 39 58 8 7	Run LX39	3390 V
		HIC nbr	Width	HIC nbr			r Width	HIC nbr	Width
H IC	X-Axis			84.55			75.00		
				0.04			93.00		
				14.81				21.08	44.00
	ant HIC	65.33	114.00	112.04					
Nesui C	ant nit	05.55	114.00	112.04	94.50	153.53	83.50	155.58	83.00





SUBJECT H00131
*** Plus Y Sled Runs ***

DO

		VID	
5 G-Level		6 G-Leve	7 G-Level
Run LX4089	Run LX4109	/R\un_LX413/8	Run LX4124
Max Min	Max Min	/Max Min	Max Min
Force X-Axis 43.83 -213.44			50.69 -190.52
Force Y-Axis 412.69 -46.53		403.64 -78.89	403.69 -88.93
Force Z-Axis 54.85 -198.98			69.86 -323.39
Force Result 440.67 39.02		443.29\ 43.57	494.31 39.76
10100 Nesulu 440.07 : 35.02	37 J - TE 1 TE - 12	773.23 73.37	454102 05170
5 G-Level	6 G-Level	6 6-1/9/91	7 G-Level
	Run LX4109	Run LX4138	Run LX4124
Max Min	Max Min	Max V Min	Max Min
Torque X-Axis 2.67 -32.58			7.09 -33.13
Torque Y-Axis 7.09 -11.98	7.10 -11.02	6.33 +11.24°	8.92 -11.28
Torque Z-Axis 9.57 -1.86	. 11.70 -2.91	$12.67 / -3 \setminus 13$	12.95 -4.86
	35.33 0.07	36.78 / .₹1	35.41 0.25
1.1.1			
5 G-Level	6 G-Level	\ 6 G-Leve1 \	7 G-Level
	Run LX4109	Run LX4138	Run LX4124
	HIC nbr/ Width	HIC nor Width	HIC nbr Width
1110(1151) 1110011	1110	110 119. 11. 40.1.	1110 1101
HIC X-Axis 11.95 94.00	12.65 94.00	10.85 97.50	13.02 84.50
HIC Y-Axis 0.24 129.00		0.52 73.00	0.41 68.00
HIC Z-Axis 1.19 59.50		3.18 67.00	
Resultant HIC 15.28 95.00			18.09 94.00
Resultant HIC 13.20 33.00	17.05 101.50	10.52 107.50	10.09 34.00
**************************************	** Minus X / Plus	V +++	and the second s
en e	"" Fillus X / Plus	1	
. 7 C Laval	10 0 1 0407	•	

		7 G-l Run L)	_eve1 (4242	10 G- Run L	Level X4251
		Max	Min	Max	Min
Force	X-Axis	6.81	-395.81	98.05	-700.19
Force	Y-Axis	274.63	-2.14	394.24	-81.61
Force	Z-Axis	51.17	-155.54	42.81	-467.41
Force	Result	479.87	22.17	877.93	21.56
,,		7 G-1	_evel	10 G-	Level

**		7 G-L	evel	10 G-L	.evel
		Run LX4242		Run LX4251	
		Max	Min	Max	Min
Torque		0.20	-20.71	6.91	- 28 . 93
Torque			- 27 . 23	7.37	- 44.60
Torque	Z-Axis	7.71	-2.34	12.52	-5.17
Torque	Result	31.48	0.17	51.52	0.35

		7 G-Le	evel	10 G-Le	vel
		Run-LX		Run_LX4	251
		HIQ nbr		HIC:nbr/	Width
H IC		15\87		55.08	69.50
	Y-Axis	0.13	77.00	2.15	54.00
	Z-Axis	3.50	67.50	13.18	57.50
Resulta	ant HIC	22.42	113.00	83.28	106.50



*** Head Anatomical Configuration ***

Head Mass: 4.523 Kg.

Head Center of Gravity: X = +0.0084 Y = -0.0006 Z = +0.0318 Meters

Head / Neck Center of Gravity: X = +0.0190 Y = +0.0000 Z = +0.5800 Meters

Eignvalues: 1 = +0.02259 2 = +0.02415 3 = +0.01572

•			evel 3989	13 G-L Run LX				15 G-Le Run LX	
		Max	Min	Max	Min	Max	Min	Max	Min
		55.43	-691.57		1535.00		199.90	143.99-	1395.33
	Y-Axis			64.71					
Force	Z-Axis	80.33	-317.61	42.95	-983.66	44.89	-629.76	44.56	-801.69
Force	Result	750.09	22.59	1823.22	4.61	1252.74	16.66	1514.52	8.89
		10 G-L	eve1	13 G-L	evel	14 G-L	evel	15 G-Lev	el
		Run LX	3989	Run LX	3950	Run LX	3957	Run LX	3982
		Max	Mi n	Max	″Min	Max	Min	Max	Min
Torque	X-Axis	6.39	-0.86	11.19	-15.49	7.80	-3.22	11.73	-6.22
			- 39.89					13.58	
							-5.25	1.23	-4.15
Torque	Result	40.37	0.10	68.58	0.11	56.59	0.34	75.71	0.11
		10 G-L	.evel	13 G-L	evel	14 G-L	evel	15 G-Lev	el
		HIC nbr	Width	HIC nbr	Width	HIC nb	r Width	HIC nbr	Width
1		Run LX	3989	Run LX	3950	Run LX	3957	Run LX	3982
	X-Axis		81.50		72.50	118.32	74.50	112.06	65.00
			184.00		187.00	0.11	212.00	0.08	66.50
			75.50	16.61	19.50	13.42	41.00	29.03	41.00
Result	ant HIC	50.01	94.50	126.49	83.50	146.99	81.00	167.47	83.00



SUBJECT H00132 *** Plus Y Sled Runs ***

		_	_		_	
		5 G-L	evel	6 G-L	.evel	7 G-Level
		Run LX	4090	Run L	(4110	Run LX4128
		Max		Max	Min	Max Min
Force	Y=Avic	42 26	_178 27	35.75	-315 75	60.02 -287.66
Tâia a	V-UVI2	201 50	10.27	111 17-	-313.73	392.60 -138.20
Force	Z-AX1S	77.41	-168.80	/3.51	-320.10	101.81 -301.20
Force:	Result	343.08	38.09	539.94	28.51	495.36 44.30
						• •
	n e, e 🛥 🕺	5 G-L	eve1	6 G-l	_evel	7 G-Level Run LX4128
		Run IX	4090	Run 1)	(4110	- Run 1 X 4128
		May	Min	May	Min	May Min
Tomario	V Avia	1 02	10.70	7.40	20.24	Max Min 10.84 -27.67
Torque	X-AXIS	1.92	-19.70	7.49	-29.34	10.04 -24.07
lorque	Y-AX1S	3.46	-8.27	5.56	-13./9	5.33 -15.05
Torque	Z-Axis	8.00	-1.32	*11.35	-2. 96	13.85 -3.81
Torque	Result	22.49	0.23	33.73	0.27	32.89 0.26
-						
	•	5 G-I	evel	6 G-1	evel	7 G-Level Run LX4128
	*	Run I Y	4090	Run I	X4110	Dun 1 Y / 1 2 R
		LIC nhr	111111 h	UIC pho	1.11.0 1.11.0+b	Run LX4128 HIC nbr Width 12.53 94.00
11.10	V 8	HIC HOL	104.00	14 70	101 00	HIC HOT WICCH
HIC	X-AXIS	5.94	124.00	14./8	101.00	12.53 94.00
H IC	Y-AX1S	0.09	214.50	0.23	26.50	0.13 216.00
H IC	Z-Axis	1.74	80.00	2.01	54.00	3.69 61.00
Result	ant HIC	9.01	137.50	19.71	104.00	18.77 104.50
	:		**	* Minus	X / Plus	γ ***
						The second second
	** .				· . · · · ·	the state of the s
•	***	7 G-I	evel	10 G-	level	11 G-Level
Fores	e de la companya de l	7 G-L	evel	10 G-	Level	11 G-Level
Fores		Run LX	4261	Run L	X4297	Run LX4306
		Run LX Max	4261 Min	Run L	X4297 Min	Run LX4306 Max Min
Force	X-Axis	Run EX Max 26.95	4261 Min -568.61	Run L: Max 64.44	X4297 Min -752.94	Run LX4306 Max Min 31.41 -713.83
Force Force	X-Axis Y-Axis	Run EX Max 26.95 299.74	4261 Min -568.61 -60.54	Run L Max 64.44 311.01	X4297 Min -752.94 -104.52	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08
Force Force	X-Axis Y-Axis Z-Axis	Run EX Max 26.95 299.74 44.64	4261 Min -568.61 -60.54 -202.31	Run L Max 64.44 311.01 98.66	X4297 Min -752.94 -104.52 -295.38	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87
Force Force	X-Axis Y-Axis Z-Axis	Run EX Max 26.95 299.74 44.64	4261 Min -568.61 -60.54 -202.31	Run L Max 64.44 311.01 98.66	X4297 Min -752.94 -104.52 -295.38	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87
Force Force	X-Axis Y-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44	4261 Min -568.61 -60.54 -202.31 14.79	Run L' Max 64.44 311.01 98.66 848.15	X4297 Min -752.94 -104.52 -295.38 17.48	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42
Force Force	X-Axis Y-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44	4261 Min -568.61 -60.54 -202.31 14.79	Run L' Max 64.44 311.01 98.66 848.15	X4297 Min -752.94 -104.52 -295.38 17.48	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42
Force Force	X-Axis Y-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44	4261 Min -568.61 -60.54 -202.31 14.79	Run L' Max 64.44 311.01 98.66 848.15	X4297 Min -752.94 -104.52 -295.38 17.48	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42
Force Force	X-Axis Y-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max	4261 Min -568.61 -60.54 -202.31 14.79 evel	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min
Force Force Force	X-Axis Y-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306
Force Force Force Torque	X-Axis Y-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82
Force Force Force Torque	X-Axis Y-Axis Z-Axis Result X-Axis Y-Axis	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51	Run L Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 (I) G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70
Force Force Force Torque Torque Torque	X-Axis Y-Axis Z-Axis Result X-Axis Y-Axis Z-Axis	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L' 6.62 5.30 10.91	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82
Force Force Force Torque Torque Torque	X-Axis Y-Axis Z-Axis Result X-Axis Y-Axis	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51	Run L Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59
Force Force Force Torque Torque Torque	X-Axis Y-Axis Z-Axis Result X-Axis Y-Axis Z-Axis	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L' 6.62 5.30 10.91	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59
Force Force Force Torque Torque Torque	X-Axis Y-Axis Z-Axis Result X-Axis Y-Axis Z-Axis	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88 40.70	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31 0.46	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30 10.91 49.07	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28 0.52	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59 51.65 0.62
Force Force Force Torque Torque Torque	X-Axis Y-Axis Z-Axis Result X-Axis Y-Axis Z-Axis	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88 40.70 7 G-L	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31 0.46	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30 10.91 49.07	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28 0.52	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59 51.65 0.62
Force Force Force Torque Torque Torque	X-Axis Y-Axis Z-Axis Result X-Axis Y-Axis Z-Axis	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88 40.70 7 G-L Run LX	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31 0.46	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30 10.91 49.07	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28 0.52 Level X4297	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59 51.65 0.62
Force Force Force Torque Torque Torque	X-Axis Y-Axis Z-Axis Result X-Axis Y-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88 40.70 7 G-L Run LX HIC nbr	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31 0.46 evel 4261 c Width	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L' 6.62 5.30 10.91 49.07 10 G- Run L HIC nbr	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28 0.52 Level X4297 Width	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59 51.65 0.62 If G-Level Run LX4306 HIC nbr Width
Force Force Force Torque Torque Torque	X-Axis Y-Axis Z-Axis Result X-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88 40.70 7 G-L Run LX HIC nbr 36.62	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31 0.46 evel 4261 Width 103.50	Run L Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30 10.91 49.07 10 G- Run L HIC nbr 45.65	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28 0.52 Level X4297 Width 77.00	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59 51.65 0.62 If G-Level Run LX4306 HIC nbr Width 50.09 84.00
Force Force Force Torque Torque Torque HIC HIC	X-Axis Y-Axis Z-Axis Result X-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88 40.70 7 G-L Run LX HIC nbr 36.62 0.46	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31 0.46 evel 4261 Width 103.50 44.00	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30 10.91 49.07 10 G- Run L HIC nbr 45.65 1.22	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28 0.52 Level X4297 Width 77.00 32.50	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59 51.65 0.62 If G-Level Run LX4306 HIC nbr Width
Force Force Force Torque Torque Torque Torque HIC HIC HIC	X-Axis Y-Axis Z-Axis Result X-Axis Z-Axis Result X-Axis Y-Axis Z-Axis	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88 40.70 7 G-L Run LX HIC nbr 36.62 0.46 3.15	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31 0.46 evel 4261 Width 103.50	Run L Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30 10.91 49.07 10 G- Run L HIC nbr 45.65	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28 0.52 Level X4297 Width 77.00	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59 51.65 0.62 If G-Level Run LX4306 HIC nbr Width 50.09 84.00
Force Force Force Torque Torque Torque Torque HIC HIC HIC	X-Axis Y-Axis Z-Axis Result X-Axis Z-Axis Result	Run LX Max 26.95 299.74 44.64 650.44 7 G-L Max Run LX 4.35 2.03 8.88 40.70 7 G-L Run LX HIC nbr 36.62 0.46	4261 Min -568.61 -60.54 -202.31 14.79 evel Min 4261 -20.38 -35.51 -1.31 0.46 evel 4261 Width 103.50 44.00	Run L' Max 64.44 311.01 98.66 848.15 10 G- Max Run L 6.62 5.30 10.91 49.07 10 G- Run L HIC nbr 45.65 1.22	X4297 Min -752.94 -104.52 -295.38 17.48 Level Min X4297 -18.26 -45.39 -4.28 0.52 Level X4297 Width 77.00 32.50	Run LX4306 Max Min 31.41 -713.83 341.89 -74.08 45.72 -301.87 834.00 26.42 If G-Level Max Min Run LX4306 4.00 -21.82 3.26 -46.70 10.06 -2.59 51.65 0.62 If G-Level Run LX4306 HIC nbr Width 50.09 84.00 0.57 28.00



*** Head Anatomical Configuration ***

Head Mass:	4.170 Kg.	· .					
Head Center	4.170 Kg. of Grávity:	χ =	+0.0082	Y =	-0.0005	Z = +0.03	310 Meters
Head / Neck	Center of Gravity	: X =	+0.0190	Y =	+0.0000	Z = +0.58	300 Meters
	1 = +0.01973						
			•				
Principal	Axis Matrix		Momen	t of	inertia	matrix in	A.C.S.
+0.82900 +0	.00000 +0.55920		+0.0	17853	3 +0.000	000 +0.00	02781
+0.00000 +1	.00000 +0.00000					100 1+0 00	

-0.55920 +0.00000 +0.82900

*** Minus X Sled Runs ***

+0.002781 +0.000000 +0.015605

		Run LX Max	Min	Run LX: Max	3951 Min		3963 Mi n	15 G-L Run LX Max	3986 Mi n
				96.06		115.21 -			-552.93
				70.55 40.78		85.05			-99.08
Force				1122.77		1147.43	-867.30	671.05	-414.60 2 96
, 0, 00	. ·	370.32	. 		11.00	1147.40	10.07	0/1.03	2.30
		10 G-L	evel	13 G-L	evel	14 G-Le	evel	15 G-Lev	el
			3998		3951	Run LX	3963	Run LX	3986
		Max	Mi n	Max	Min	Max	Min	Max	Min
				6.14				9.22	
		3.14		9.29	-48.99			3.14	
			-1.47			3.96			-1.47
Torque	Result	39.15	0.15	49.06	0.03	56.19	0.13	39.15	0.15
				13 G-L			evel	15 G-Lev	
			3998				3963	Run LX	
			Width	HIC nbr			r Width	HIC nbr	
	X-Axis				76.50		77.50	131.30	
	Y-Axis		73.00	0.06	216.00		144.00	0.20	
H IC	Z-Axis		62.50	17.29	48.00	15.57	50.50	23.83	41.50
Kesult	ant HIC	55.32	106.50	120.17	94.00	125.77	89.00	177.62	88.50



SUBJECT H00133 *** Plus Y Sled Runs ***

Force X-Axis	Run LX4093 Max Min 43.51 -163.40 364.71 -34.23	6 G-Level Run LX4111 Max Min 27.00 -188.44 395.26 -51.60	Run LX4125 Max Min 24.50 -274.48 577.36 -108.84
Force Result	380.65 40.25	71.89 -276.20 444.90 30.88	647.16 36.46
	Max Min 2.84 -28.16 4.70 -10.12 9.38 -0.27 30.38 0.49	6 G-Level Run LX4111 Max Min 3.91 -33.20 3.30 -9.25 10.32 -1.15 35.42 0.69	Max Min 8.71 -44.60 4.26 -12.65 16.68 -2.43 49.05 0.64
HIC X-Axis HIC Y-Axis HIC Z-Axis Resultant HIC	5 G-Level Run LX4093 HIC nbr Width 11.62 104.50 0.18 148.50 0.63 268.00 13.74 106.00	6 G-Level Run LX4111 HIC nbr Width 16.36 97.00 0.25 135.00 1.72 61.50 21.05 102.50	7 G-Level Run LX4125 HIC nbr Width 24.85 74.00 0.23 79.50 3.95 44.00 32.93 78.50
Production Symposium (1997). The second of	***	Minus X / Plus Y	***
စီးဂျွမ္းကို သို့မရှိသည်။ သို့သည်းသည် အချည်သည်	7 G-Level	10 G-Level Run LX4240	
Force Y-Axis Force Z-Axis	3.74 -343.93	11.38 -447.93 499.11 -39.79 52.51 -273.00	
Torque X-Axis	7 G-Level Run LX4236 Max Min	Run LX4240 Max Min	
Torque Y-Axis Torque Z-Axis Torque Result	0.34 -20.87 9.18 -0.11	2.80 -26.65 0.80 -25.14 11.45 -0.94 36.51 0.22	
HIC X-Axis HIC Y-Axis HIC Z-Axis Resultant HIC	0.18 45.50 1.04 115.00	10 G-Level Run LX4240 HIC nbr Width 39.86 104.50 0.33 44.50 3.98 57.50 50.50 106.50	-



SUBJECT HOO134

*** Head Anatomical Configuration ***

Head Mass: 4.278 Kg.

Head Mass: 4.2/8 kg. Head Center of Gravity: X = +0.0083 Y = -0.0005 Z = +0.0313 Meters Head / Neck Center of Gravity: X = +0.0190 Y = +0.0000 Z = +0.5800 Meters Eignvalues: 1 = +0.02059 2 = +0.02201 3 = +0.01433

Principal Axis Matrix Moment of inertia matrix in A.C.S. +0.018631 +0.000000 +0.002902 +0.000000 +0.022010 +0.000000 +0.82900 +0.00000 +0.55920 +0.00000 +1.00000 +0.00000 **-0.55920 +0.00000 +0.82900** +0.002902 +0.000000 + +0.016287

		10 G-L Run LX	eve1 3993	13 G-L Run LX		14 G-L Run LX	evel 3968	15 G-L Run LX	
		Max	Min	Max	Min	Max	Min	Max	Min
Force	X-Axis	28.56	-629.12	81.13	-969.39	92.79	-961.99	100.82	-994.27
Force	Y-Axis	20.05	-42.76	30.54	- 84.36	57.22	-119.35	67.90	-89.18
Force	Z-Axis	46.41	-418.24	41.61	-739.49	43.32	-826.82	42.62	-769.25
Force	Result	722.41	14.38	1089.09	+11.57	1114.39	13.86	1182.19	10.44
			evel	13 G-L	evel	14 G-L	evel	15 G-Lev	el
			3993	Run LX	3961	Run LX	3968	Run LX39	83
		Max	Min	Max	Min	Max	Min	Max	Min
				5.67	-1.91	7.27	-5.35	7.75	-3.02
		2.06		7.09	-47.83	10.04	-53.65	9.23	-55.22
			-0. 68	1.50	-2.65	2.39	-4.18	1.05	-1.71
Torque	Result	39.25	+0.05	47.99	+0.05	53.72	+0.02	55.76	0.15
`*		10 G-L	evel	13 G-L	evel	14 G-L	.eve1	15 G-Lev	el
		Run LX	3993	Run LX	3961	Run LX	3968	Run LX39	83
		HIC Nbr	Width	HIC Nbr		HIC Nb	r Width	HIC Nbr	· Width
	X-Axis		80.00	96.30	67.50	93.33	67.00	137.66	71.50
	Y-Axis			0.64	200.50	0.11	121.00	0.22	175.00
H IC	Z-Axis			18.36	54.50	25.43	49.50	25.01	43.00
Result	ant HIC	66.03	103.00	127.56	89.00	134.16	87.00	186.80	84.00



SUBJECT HOO134 *** Plus Y Sled Runs ***

	5 G-L	evel	6 G-Le		7 G-Le	evel
	Run LX	4097	Run LX4	1112	Run LX4	
	Max	Min	Max	Min	Max	Min
Force X-Axi	s 20.59				60.02 -	-262.26
Force Y-Axi						
Force Z-Axi	s: 43.97	-162.33	52.70	-250.91	= 47.34 -	307.52
Force Resul						-
					•	
	5 G-L	evel 4097	6 G-L	evel	7 G-Le Run LX	evel
	Run LX	4097-	Run LX	4112	Run LX4	1126
	Max	Min	Max	Min.	Max	Min
Torque X-Axi	s 2.77	-24.35	5.53	-31.37	6.92	-31.04
Torque Y-Axi	s 2.25	-10.17	4.14	-14.51	8.02	-14.86
Torque Z-Axi	s 7.90	-0.25	10.94	-2.23	10.66	-2.81
Torque X-Axi Torque Y-Axi Torque Z-Axi Torque Resul	t 26.57	+0.34	33.02	+0.45	34.45	+0.04
	5 G-L	evel	6 G-Le Run LX	evel	7 G-Le	
	Run LX	4097	Run LX	4112		
	HIC Nor	Width	HIC Nbr	Width	HIC No	r Width
HIC X-Axi HIC Y-Axi	s 11.15	114.50	13.69	103.50	16.27	86.50
HIC Y-Axi	s 0.08	133.00	0.06	143.50	0.21	112.00
HIC Z-Axi	s 1.14	70.00	0.98	69.50	2.08	55.00
HIC Y-Axi HIC Z-Axi Resultant HI	C 13.70	116.50	15.89	105.50	20.62	91.00
		. [<u>]</u>	5-			• • • • •
a Article			* Minus			
	0 6 1					~ ~
	9 G-L	evel	10 G-L	evel	11 G-Le	evel
Homes LAAVI Homes Da	Kun LX	evel 4264	10 G-L Run LX	evel 4298	11 G-Le Run LX	4307
Force V.Avi	Kun LX Max	evel 4264 Min	10 G-L Run LX Max	evel 4298 Min	11 G-Le Run LX Max	4307 Min
Force X-Axi	Max s 30.28	evel 4264 Min -520.00	10 G-L Run LX Max 37.18	evel 4298 Min -589.15	11 G-Le Run LX Max 43.68	4307 Min -680.55
Force Y-Axi	Max s 30.28 s 356.98	evel 4264 Min -520.00 -48.65	10 G-L Run LX Max 37.18 341.57	evel 4298 Min -589.15 -49.29	11 G-Le Run LX Max 43.68 361.52	4307 Min -680.55 -86.75
Force Y-Axi Force Z-Axi	Max s 30.28 s 356.98 s 42.31	evel 4264 Min -520.00 -48.65 -337.14	10 G-L Run LX Max 37.18 341.57 43.75	evel 4298 Min -589.15 -49.29	11 G-Le Run LX Max 43.68 361.52 42.29	4307 Min -680.55 -86.75 -631.21
Force Y-Axi	Max s 30.28 s 356.98 s 42.31	evel 4264 Min -520.00 -48.65 -337.14	10 G-L Run LX Max 37.18 341.57 43.75	evel 4298 Min -589.15 -49.29	11 G-Le Run LX Max 43.68 361.52 42.29	4307 Min -680.55 -86.75 -631.21
Force Y-Axi Force Z-Axi	Max s 30.28 s 356.98 s 42.31 t 681.84	evel 4264 Min -520.00 -48.65 -337.14 25.56	10 G-L Run LX Max 37.18 341.57 43.75 755.83	evel 4298 Min -589.15 -49.29 -473.28 +14.07	11 G-Le Run LX4 Max 43.68 361.52 42.29 924.77	4307 Min -680.55 -86.75 -631.21 12.78
Force Y-Axi Force Z-Axi	Max s 30.28 s 356.98 s 42.31 t 681.84	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel	10 G-L Run LX Max 37.18 341.57 43.75 755.83	evel 4298 Min -589.15 -49.29 -473.28 +14.07	11 G-Le Run LX Max 43.68 361.52 42.29 924.77	4307 Min -680.55 -86.75 -631.21 12.78
Force Y-Axi Force Z-Axi	Run Lx Max s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307
Force Y-Axi Force Z-Axi Force Resul	8un Lx Max s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX Max	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min
Force Y-Axi Force Z-Axi Force Resul	Run LX Max s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX Max s 4.33	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99	11 G-Le Run LXA Max 43.68 361.52 42.29 924.77 11 G-Le Run LXA Max 6.58	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi	s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX Max s 4.33 s 2.47	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -32.52	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi Torque Z-Axi	8un LX Max s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX Max s 4.33 s 2.47 s 10.54	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -32.52 -0.90	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15 10.82	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92 -1.49	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69 12.12	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53 -0.88
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi	8un LX Max s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX Max s 4.33 s 2.47 s 10.54	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -32.52	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi Torque Z-Axi	8un LX Max s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX Max s 4.33 s 2.47 s 10.54	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -32.52 -0.90 +0.06	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15 10.82	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92 -1.49 +0.17	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69 12.12 48.55	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53 -0.88 +0.03
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi Torque Z-Axi	9 G-L Run LX Max s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX Max s 4.33 s 2.47 s 10.54 t 41.17	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -32.52 -0.90 +0.06 evel	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15 10.82 42.17	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92 -1.49 +0.17 evel	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69 12.12 48.55	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53 -0.88 +0.03
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi Torque Z-Axi	9 G-L Run LX 8 356.98 8 42.31 t 681.84 9 G-L Run LX Max 8 4.33 8 2.47 8 10.54 t 41.17	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -0.90 +0.06 evel 4264	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15 10.82 42.17	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92 -1.49 +0.17 evel 4298	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69 12.12 48.55	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53 -0.88 +0.03 evel 4307
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi Torque Z-Axi	9 G-L Run LX 8 356.98 8 42.31 t 681.84 9 G-L Run LX 8 4.33 8 2.47 8 10.54 t 41.17 9 G-L Run LX HIC Nbr	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -32.52 -0.90 +0.06 evel 4264 Width	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15 10.82 42.17 10 G-L Run LX HIC Nbr	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92 -1.49 +0.17 evel 4298 Width	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69 12.12 48.55 11 G-Le Run LX HIC Nb	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53 -0.88 +0.03 evel 4307 r Width
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi Torque Z-Axi Torque Resul HIC X-Axi HIC Y-Axi	9 G-L Run LX Max s 30.28 s 356.98 s 42.31 t 681.84 9 G-L Run LX Max s 4.33 s 2.47 s 10.54 t 41.17 9 G-L Run LX HIC Nbr s 40.91	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -32.52 -0.90 +0.06 evel 4264	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15 10.82 42.17 10 G-L Run LX	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92 -1.49 +0.17 evel 4298 Width 74.50	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69 12.12 48.55 11 G-Le Run LX HIC Nb 70.22	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53 -0.88 +0.03 evel 4307 r Width 75.00
Force Y-Axi Force Z-Axi Force Resul Torque X-Axi Torque Y-Axi Torque Z-Axi Torque Resul HIC X-Axi	8un LX Max \$ 30.28 \$ 356.98 \$ 42.31 \$ 681.84 9 G-L Run LX Max \$ 4.33 \$ 2.47 \$ 10.54 \$ 41.17 9 G-L Run LX H IC Nbr \$ 40.91 \$ 0.35 \$ 5.30	evel 4264 Min -520.00 -48.65 -337.14 25.56 evel 4264 Min -28.12 -32.52 -0.90 +0.06 evel 4264 Width 82.50	10 G-L Run LX Max 37.18 341.57 43.75 755.83 10 G-L Run LX Max 3.69 3.15 10.82 42.17 10 G-L Run LX HIC Nbr 45.56 0.23	evel 4298 Min -589.15 -49.29 -473.28 +14.07 evel 4298 Min -23.99 -36.92 -1.49 +0.17 evel 4298 Width	11 G-Le Run LX Max 43.68 361.52 42.29 924.77 11 G-Le Run LX Max 6.58 3.69 12.12 48.55 11 G-Le Run LX HIC Nb 70.22 0.66	4307 Min -680.55 -86.75 -631.21 12.78 evel 4307 Min -29.66 -42.53 -0.88 +0.03 evel 4307 r Width



*** Head Anatomical Configuration ***

Head Mass: 3.791 Kg.

Head Center of Gravity: X = +0.0080 Y = -0.0005 Z = +0.0300 MetersHead / Neck Center of Gravity: X = +0.0190 Y = -0.0000 Z = +0.5800 MetersEignvalues: 1 = +0.01683 Z = +0.01800 Z = +0.01171

+0.82900 +0.00000 +0.55920 +0.000000 +0.002374 +0.00000 +0.00000 +0.00000 +0.000000 +0.000000 +0.002374 +0.0022374 +0.0022374 +0.0022374 +0.0022374 +0.0022374 +0.0022374 +0.0022374 +0.0022374 +0.002222 +0.002222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.00222 +0.0022 +0.0022 +0.0022 +0.0022 +0.002

						14 G-L Run LX		15 G-L Run LX	
			Min				Min		
						114.80-			-840.30
								16.60	
								36.55	
		717.10	6.56	891.40	10.25	1294.03	11.38	955.28	9.40
		* *	4	31 34	ž.	14 G-L	••		
		10 G-L	.evel	13 G-L	.evel	14 G-L	evel	15 G-Lev	'el
			3916		3955	Run LX	3965	Run LX	(3970
		Max					Min		
Torque	X-Axis	8.27	-2.39	<i>-</i> 9.50	-2.26	9.68	-5.45	18.09	-1.70
Torque	Y-Axis	5.41	-33.14	7.63	- 44 . 79	8.78	-68.54	8.68	-49.17
		0.94	-1.29				-3.70	2.05	-4.10
Torque	Result	33.21	0.13	44.82	0.24	68.58	0.17	49.35	0.27
		10 G-I	.evel	13 G-I	Evel	1.4 GI	eve1	15 G-Lev	امر
**			3916					Run L	
			Width		Width		r Width		
H IC	X-Axis				75.50		74.00		
								0.06	
				16.62	49 50	22 61	100 50	24.95	45 00
	ant HIC	66.22							
Kesuit	ant nic	00.22	10/.50	120.46	87.50	162.35	84.00	154.17	86 .50



SUBJECT H00135 *** Plus Y Sled Runs ***

		6 G-Level	
		Run LX4114	
Force V Avie	Max Min	Max Min	Max Min
Force X-AXIS	31.37 -144.94	30.70 -204.51	52.96 -254.57
Force 7-Axis	200.20 -01.90 EA 27 1A0 02	329.41 -91.10	303.00 -120.31 -76 10 275 72
Force Pacult	225 10 20 00	375.44 32.69	= 76.10 -275.73
rorce Result	323.10 30.09	3/3.44 - 32.09	447.19 30.17
	5 G-Level	6 G-Level Run LX4114	7 G-Level
	Run LX4095	Run LX4114	Run LX4131
	Max Min	Max Min	Max Min
Torque X-Axis	5.34 -21.65	6.21 -23.75	8.84 -28.43
Torque Y-Axis	3.07 -8.76	6.21 -23.75 3.55 -9.52 -7.91 -1.94 26.48 0.27	7.36 -12.95
Torque Z-Axis	7.75 -1.17	- 7.91 -1.94	10.66 -3.03
Torque Result	23.96 0.23	26.48 0.27	32.92 0.33
	5 G-Level	6 G-Level Run LX4114 HIC Nbr Width	7 G-Level
	Run LX4095	Run LX4114	Run LX4131
	HIC Nbr Width	HIC Nbr Width	HIC Nbr Width
HIC X-Axis	11.42 117.00	14.85 102.50	40.85 81.00
		0.15 141.50	
		1.30 48.50	
Resultant HIC	13.77 121.00-	18.28 102.00	50.76 101.00
	**	* Minus V / Dlus	V +++
		" Fillus X / Flus	1
. '	9 G-Level	10 G-Level	
, '		* Minus X / Plus 10 G-Level Run LX4316	
	Max Min	Max Min	
	Max Min	Max Min	
Force X-Axis Force Y-Axis	Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis	Max Min	Max Min	
Force X-Axis Force Y-Axis	Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis	Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis	Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis Force Result	Max Min 9 G-Level Run LX4314 Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis Force Result	Max Min 9 G-Level Run LX4314 Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis	Max Min 9 G-Level Run LX4314 Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis Torque Z-Axis	Max Min 9 G-Level Run LX4314 Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis	Max Min 9 G-Level Run LX4314 Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis Torque Z-Axis	Max Min 9 G-Level Run LX4314 Max Min	Max Min	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis Torque Z-Axis	Max Min 9 G-Level Run LX4314 Max Min	Max Min 10 G-Level Run LX4316 Max Min	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis Torque Z-Axis	Max Min 9 G-Level Run LX4314 Max Min 9 G-Level	Max Min 10 G-Level Run LX4316 Max Min 10 G-Level	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis Torque Z-Axis Torque Result HIC X-Axis	Max Min 9 G-Level Run LX4314 Max Min 9 G-Level Run LX4314 HIC Nbr Width 40.85 81.00	Max Min 10 G-Level Run LX4316 Max Min 10 G-Level Run LX4316 HIC Nbr Width 51.32 79.00	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis Torque Z-Axis Torque Result HIC X-Axis HIC Y-Axis	Max Min 9 G-Level Run LX4314 Max Min 9 G-Level Run LX4314 HIC Nbr Width 40.85 81.00 0.32 131.00	Max Min 10 G-Level Run LX4316 Max Min 10 G-Level Run LX4316 HIC Nbr Width 51.32 79.00 0.37 162.00	
Force X-Axis Force Y-Axis Force Z-Axis Force Result Torque X-Axis Torque Y-Axis Torque Z-Axis Torque Result HIC X-Axis	Max Min 9 G-Level Run LX4314 Max Min 9 G-Level Run LX4314 HIC Nbr Width 40.85 81.00	Max Min 10 G-Level Run LX4316 Max Min 10 G-Level Run LX4316 HIC Nbr Width 51.32 79.00	



*** Head Anatomical Configuration ***

Head Mass: 4.235 Kg. Head Center of Gravity: X = +0.0083 Y = -0.0005 Z = +0.0312 Meters Head / Neck Center of Gravity: X = +0.0190 Y = +0.0000 Z = +0.5800 Meters Eignvalues: 1 = +0.02024 2 = +0.02164 3 = +0.01409

				` `				-	
	- :	10 G-L	evel	12\G-L	evel	13 G-L	.evel	14 G-L	evel
		Run LX	3918	Run \LX	3942	Run LX	3953	Run LX	3962
_		Max	Min	Max \	Min	Max	Min	Max	Min
	X-Axis		•	• \	. 1.	•	•	•	•
Force	Y-Axis	•	•	•	١١.	•	•	•	
	Z-Axis		• 500		1 1.	_		_	_
Force	Result		_	7 1 Tab		•	•	•	•
10100	NC Sui V	• . & %.	• 5. E	•	//:	•	•	•	•
		10 G-L	evel	12 G-L	evel	13 G-L	.eve1	14 G-L	evel
		Run LX	3918	Run LX	3942	Run LX		Run LX	3962
		Max	Mi n	Max	Min	Max	Min	Max	Min
	X-Axis		•	•	// •	•		•	•
Torque	Y-Axis	•	•	•	11.		•		
Torque	Z-Axis	•	•		/	_	_	_	_
•	Result		_	-	11	•	•	. •	•
. 0 , 4 4 6		•	•	•	11.	•	•	•	•
		•			/				
		10 G-L	evel	12 G-L	eve l	13 G-L	.eve1	14 G-L	evel
		Run LX	3918	Run LX	3942	Run LX	3953	Run LX	3962
		HIC Nbr	Width	HIC Nbr	Width		r Width	HIC Nbr	
H IC	X-Axis	48.48	91.50	65.83	92.50		83.50	99.13	85.50
H IC	Y-Axis		528.50	0.18	189.50		194.00		84.00
H IC	Z-Axis		61.00	16.22	53.50				
						19.11		14.07	120.00
Result	ant HIC	65.84	107.50	95.49	95,50	121.16	100.00	128.32	85.50



SUBJECT HOO136

+++	D1	v	C 7 - 4	D	مال مال مال
~ ~ ~	Plus	1	2160	Runs	^ X X X

		5 G-L	.eve1	6 G-L	6 G-Level		evel
		Run LX	4098	Run LX	4142	Run LX4153	
		Max	Min	Max	Min	Max	Min
H IC	X-Axis	9.42	118.00	13.37	100.00	18.48	82.00
	Y-Axis			0.36	154.50	0.53	127.50
	Z-Axis				119.00	2.64	106.50
Resul	tant HIC	11.57	124.00	16.91	104.50	24.36	

***-Minus Y / Dlus V ***

	,-		^^^-MITHUS X / PIUS Y				
		7 G-Le	evel	9 G-Le			
		Run LX4247		Run LX4	1263		
		HIC Nbr	Width	HIC Nbr	Width		
H IC	X-Axis	23.27	115.00	33.30	81.50		
H IC	Y-Axis	0.14	59.50	0.61	57.00		
				6.11			
Resul	tant HIC	27.86	112.00	47.72	109.50		



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